

ARMAX EQUATIONS IN GENERAL

$$y_t = \frac{\omega_t(L)}{\delta_t(L)} X_{t-b} + \frac{w_t(L)}{d_t(L)} I_{t-\tau} + \frac{\Theta_t(L)\theta_t(L)}{\nabla_t \nabla_t^s \Phi_t(L)\phi_t(L)} e_t,$$

where

y_t = dependent series

$\omega_t(L)$ = lagged or led polynomial of ω_t

$\theta_t(L)$ = nonseasonal moving average polynomial

$\Theta_t(L)$ = seasonal moving average polynomial

∇_t = first difference

∇_t^s = seasonal difference

$\phi_t(L)$ = autoregressive polynomial

$\Phi_t(L)$ = seasonal autoregressive polynomial

X_{t-b} = time varying parameters (prewhitened and differenced if nec.) b —time lag

$I_{t-\tau}$ = computer based automatic intervention detection and modeling τ —time lag

(outliers, seasonal pulses, local trends, level shifts, etc.)

e_t = disturbance